

ESIM-FCT1

Coiled Tubing Simulation Training System

Technical Specification

1. System Introduction

The coiled tubing simulation training system is developed by Chengdu Esimtech Petroleum Equipment Simulation Technology Exploitation Co., Ltd. It is the simulation training system with advanced technology, and can satisfy training demand in the industry.

The coiled tubing simulation training system is the product combining petroleum engineering technology with computer technology. Now the system can provide the common downhole operation and accident treating training items such as drilling bridge plug, sand washing, gas-lift discharge, etc. It is mainly used for training new personnel, coiled tubing operator, coiled tubing team leader, etc. Through the training with the system, trainees can master the basic operation of coiled tubing, common technology process of coiled tubing and common accidents and troubles treating in the process of coiled tubing.

There are abundant mathematical models to simulate various parameters in coiled tubing operation, such as circulation pressure, tubing weight, WOB, tubing speed, as well as the relations between these parameters, to reach the same effect of the real coiled tubing operation. The parameters can be set freely in the system, such as coiled tubing parameter, tubing parameter, screw pump parameter, BOP parameter, well structure, etc. which makes the training more targeted. The system can also simulate common downhole accident during coiled tubing operation, and instructor can insert the accident at any time. Through the phenomenon, trainees judge and handle the accident, so as to improve their skill of judging and handling accidents. The system software is non-sequence structure, and can simulate various operation of coiled tubing, which makes the system closer to reality. The site scene constructed by virtual reality technology, displayed through 3D animation, combined with vivid sound effect, makes up an immersive training environment.

The whole system consists of coiled tubing console, display system, graphics system and accessory software system. The system console is quite similar to the real coiled tubing console. The layout, operation method and parameter display of the console panel is exactly the same is real product. The hardware control adopts industrial PLC, which ensures the reliability of the system.

2. System Component

2.1 System main hardware

1) Coiled tubing console

Coiled tubing is as shown in the following figure. The control and display on the console are the same as the real coiled tubing device. It can simulate the control of injector, BOP, injector pressure adjusting, drum control, etc. According to the operation, the system displays parameters at real time,

such as circulation pressure, tubing weight, wellhead pressure, injector pressure, injector motor pressure, injector pump pressure, stripper pressure, drum drive pressure, BOP system pressure, tubing drum pressure, injector chain pressure, etc.



Figure 1 Coiled tubing console

System layout
 System layout effect picture is as shown in the following figure:



Figure 2 System layout

3) System configuration and parameters

Item	Configuration
Parameter computer	CPU: I5 or the same; Memory: 16G; Hard disk: SSD 240G
Master control computer	CPU: I7 or the same; Memory: 16G; Hard disk: SSD 240G
Graphic computer	CPU: I7 or the same; Graphic card: GTX1660 Super or the same; Memory: 16G; Hard disk: SSD 240G
Graphic screen	80-inch LCD screen
Sound effect system	Sound effect system: two-channel speaker, sound mixer, amplifier
Printer	HP printer*1
Equipment cabinet	Totem cabinet
Table and chair	Table*1; Chair*1

2.2 System Software

Master control software

- 1) Platform software module
- 2) Instructor console software module
- 3) Exercise system software module
- 4) Snapshot managing module
 - a) Well structure configuration
 - b) Coiled tubing configuration
 - c) Reel configuration
 - d) Wellsite device configuration
 - e) Fluid configuration
 - f) Downhole tool configuration
 - g) Production string configuration
- 5) Problem and troubles software module
- 6) Sound effect control module software
- 7) Parameter display module
- 8) Device state display module
- 9) Fatigue lifespan analysis module
- 10) System diagnostic module
- 11) System correction module
- 12) Language shifting module
- 13) Unit shifting module

14) Student management and automatic scoring software module

Parameter software

- 1) State monitoring module
- 2) Data monitoring module
- 3) Curve view module
- 4) Lifespan curve module
- 5) Unit selecting module
- 6) Operation command module

Graphics software

- 1) 3D scenario displaying module
- 2) Injector perspective displaying module
- 3) Reel perspective displaying module
- 4) BOP perspective displaying module
- 5) Stripper perspective displaying module
- 6) Well trajectory displaying module
- 7) Downhole tool displaying module
- 8) Problem phenomenon and treatment displaying module

2.3 Functions and Features

- 1) This simulation training system takes real coiled tubing system as prototype. The levers, meters and switches are the same as those on real equipment.
- The system adopts non-sequence simulation software structure, with no restriction on operation sequence, which simulates the mode and function of real coiled tubing console completely.
 Operator can operate the system arbitrarily as operating the real equipment.
- 3) The system provides the function of loading one snapshot, and complete various operation. Through rational setting of well condition snapshot, students can practice items such as running and pulling coiled tubing, open and close BOP, adjust injector pressure, etc. in one snapshot.
- 4) Parameters can be set freely. Instructor can set various parameters freely, such as coiled tubing parameter, screw pump parameter, tubing parameter, device parameter, etc. Instructor can set various parameters according to a real well condition, and system device, and setup corresponding well condition snapshot, making the training process closer to real site, just as training on a real well.
- 5) The system provides accidents setting functions. Instructor can insert common accident at any time during operation. Through the changes of parameters and graph, students can judge the accidents. The accidents include coiled tubing leakage, stripper leakage, coiled tubing stuck, coiled tubing speed loss, coiled tubing collapse, etc.
- 6) 3D animation simulates site scene. The animation I the system displays downhole view, surface device state and device working principle, etc. The scenes can be displayed by shifting and

splitting the screen, such as wellhead injector BOP view, coiled tubing operation cabinet view, downhole view and sewage pit view, etc.

- 7) The system provides vivid sound effect. The system can simulate various sound effect. And the sound can start and stop according to operation, working condition and graph.
- 8) Automatic scoring function. The system can give score to students' operation and their mistake automatically.
- 9) The system provides complete student management function, managing student information, operation item, scores, etc.
- 10) Important parameters can be displayed in the form of plots to show the change trend, in order to make students judge downhole condition and accident according to plots.
- 11) Flexible training process control, can pause the exercise at any time.
- 12) The system provides both metric unit and imperial unit.
- 13) The system provides Chinese and English language selection.
- 14) The scores and plots can be printed.

2.4 Current Training Items

- 1) Pulling and running tubing
- 2) Engine control operation
- 3) Reel control operation
- 4) Injector control operation
- 5) BOP control operation
- 6) Stripper control operation
- 7) Drilling bridge plug
- 8) Sand washing
- 9) Gas lift discharging
- 10) Judge and handle of downhole accidents and troubles
 - A. Coiled tubing leaking
 - B. Stripper leaking
 - C. Coiled tubing fracture
 - D. Coiled tubing collapse
 - E. Coiled tubing stuck
 - F. Coiled tubing blocked
 - G. Dynamic unit failure
 - H. Coiled tubing speed loss

3. Main Technical Parameters and Operation Environment

3.1 Technical Parameters

- 1) Power: 110~220V/50~60Hz AC
- 2) Power consumption: <6000W

3.2 Operation Environment

- 1) Area: ≥10*8.5m
- 2) Separate system power from light power.
- 3) Operation temperature: $0^{\circ}C \sim 30^{\circ}C$
- 4) Relative humidity: <90%

4. Program Running Interface

	Wellbore									
bore	Wellbore Structu	ire				Friction Coefficient				
	Name	LD(mm)	Thickness(mm)	Top(m)	Bottom(m)	Upper friction of	coefficient	Lower fri	iction coefficient	
	Surface casi			0.0		0.18		0.22		
3)	Middle casi			0.0	2817.5					
d Tubing	Producion c	• 127.36		0.0	5495.0					
ê 🛛										
		Add		Delete			Add	Delete		
E										
Equipment	- Well Traiectory >	>> Well No. 6	• Delete >>	Data						_
						ertical Length 1894.00		gth 1771.00 m Horiz	_) r
Equipment	Well Traiectory >	Well No.	Well Depth(m)	Inclination(*) Azimuth(*)	Vertical Depth(m)	DIs(*/ m) North(m)	East(m)) r
Equipment	Serial No.	Well No.	Well Depth(m)	Inclination(*	*) Azimuth(*) 0	Vertical Depth(m)	Dls(*/ m) North(m)	East(m)) r
Equipment		Well No.	Well Depth(m) 0 108.5	Inclination(* 0 0.4	*) Azimuth(*) 0 162.8	Vertical Depth(m) 0 0	Dis(*/ m 0) North(m) 0 0	East(m) 0)
	Serial No. 1 2 3	Well No. 6 6 6	Well Depth(m) 0 108.5 137	Inclination(* 0 0.4 0.6	*) Azimuth(*) 0 162.8 171	Vertical Depth(m) 0 0 0	Dis(*/ m 0 0) North(m) 0 0 0	East(m) 0 0 0)
Equipment	Serial No.	Well No. 6 6 6 6	Well Depth(m) 0 108.5 137 165.5	Inclination(* 0.4 0.6 0.6	*) Azimuth(*) 0 162.8 171 174	Vertical Depth(m) 0 0 0 0 0 0 0	Dis(*/ m 0 0 0 0) North(m) 0 0 0 0 0	East(m) 0 0 0 0 0 0 0	
Equipment	Serial No. 1 2 3 4 5	Well No. 6 6 6 6 6 6	Well Depth(m) 0 108.5 137 165.5 194	Inclination(* 0.4 0.6 0.6 0.6 0.7	 Azimuth(*) 0 162.8 171 174 172.6 	Vertical Depth(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Dis(*/ m 0 0 0 0 0) North(m) 0 0 0 0 0 0	East(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
Equipment	Serial No. 1 2 3	Well No. 6 6 6 6 6 6 6 6	Well Depth(m) 0 108.5 137 165.5 194 222.5	Inclination(* 0.4 0.6 0.6 0.7 0.7	 Azimuth(*) 0 162.8 171 174 172.6 174.2 	Vertical Depth(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Dis(*/ m 0 0 0 0 0 0 0) North(m) 0 0 0 0 0 0 0 0	East(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
Equipment	Serial No. 1 2 3 4 5 6 7	Well No. 6 6 6 6 6 6 6 6 6	Well Depth(m) 0 108.5 137 165.5 194 222.5 251	Inclination(* 0.4 0.6 0.6 0.7 0.7 0.7 0.8	 Azimuth(*) 0 162.8 171 174 172.6 174.2 176.5 	Vertical Depth(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Dis(*/ m 0 0 0 0 0 0 0 0 0) North(m) 0 0 0 0 0 0 0 0 0 0	East(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
Equipment	Serial No. 1 2 3 4 5	Well No. 6 6 6 6 6 6 6 6 6 6 6	Well Depth(m) 0 108.5 137 165.5 194 222.5 251 279.5	Inclination(* 0.4 0.6 0.6 0.7 0.7 0.7 0.8 0.8	 Azimuth(*) 0 162.8 171 174 172.6 174.2 176.5 179.5 	Vertical Depth(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Dis(*/ m 0 0 0 0 0 0 0 0 0) North(m) 0 0 0 0 0 0 0 0 0 0 0	East(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
Equipment	Serial No. 1 2 3 4 5 6 7 8 9	Well No. 6 6 6 6 6 6 6 6 6 6 6 6 6	Well Depth(m) 0 106.5 137 165.5 194 24 251 279.5 308	Inclination(* 0 0.4 0.6 0.6 0.7 0.7 0.7 0.8 0.8 1	*) Azimuth(*) 0 1628 171 174 1726 174.2 176.5 179.5 179.2	Vertical Depth(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Dis(*/ m 0 0 0 0 0 0 0 0 0 0 0 0) North(m) 0 0 0 0 0 0 0 0 0 0 0 0 0	East(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
Equipment	Serial No. 1 2 3 4 5 6 7 8 9 10	Well No. 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6	Well Depth(m) 0 108.5 137 165.5 194 222.5 251 279.5 308 336.5	Inclination(* 0.4 0.6 0.6 0.7 0.7 0.7 0.8 0.8 1 1.1	*) Azimuth(*) 0 162.8 171 174 172.6 174.2 176.5 179.5 179.5 179.2 180.6	Vertical Depth(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Dis(*/ m 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0) North(m) 0 0 0 0 0 0 0 0 0 0 0 0 0	East(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0) r
Equipment	Serial No. 1 2 3 4 5 6 7 8 9 10 11	Well No. 6 6 6 6 6 6 6 6 6 6 6 6 6	Well Depth(m) 0 108.5 137 165.5 194 222.5 251 279.5 308 336.5 365	Incination(* 0 0.4 0.6 0.6 0.7 0.7 0.8 0.8 1 1.1 1.1 1.2	*) Azimuth(*) 0 162.8 171 174 174.2 176.5 179.5 179.5 179.5 179.5 179.5 179.5 179.5 179.5	Vertical Depth(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Dis(*' m 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	North(m) O	East(m)) r
Equipment	Serial No. 1 2 3 4 5 6 7 8 9 10	Well No. 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6	Well Depth(m) 0 108.5 137 165.5 194 222.5 251 279.5 308 336.5	Inclination(* 0.4 0.6 0.6 0.7 0.7 0.7 0.8 0.8 1 1.1	Azimuti(*) 0 162.8 171 174 172.6 174.2 176.5 179.2 180.6 178.1 176.1	Vertical Depth(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Dis(*/ m 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0) North(m) 0 0 0 0 0 0 0 0 0 0 0 0 0	East(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
	Serial No. 1 2 3 4 5 6 7 8 9 10 11 12	Well No. 6 6 6 6 6 6 6 6 6 6 6 6 6	Well Depth(m) 0 108.5 137 165.5 194 222.5 251 279.5 308 336.5 365	Inclination(* 0 0.4 0.6 0.6 0.7 0.7 0.7 0.8 0.8 1 1.1 1.2 1.3	*) Azimuth(*) 0 162.8 171 174 172.6 174.2 176.5 179.5 179.2 180.6 178.1 176.1	Vertical Depth (m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Dis(*' m 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	North(m) O	East(m) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	n (

Figure 3 Coiled tubing snapshot setting interface

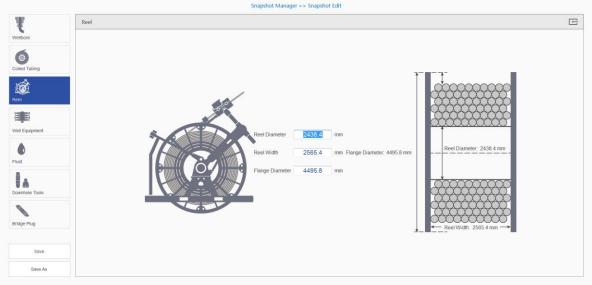


Figure 4 Reel parameter setting interface

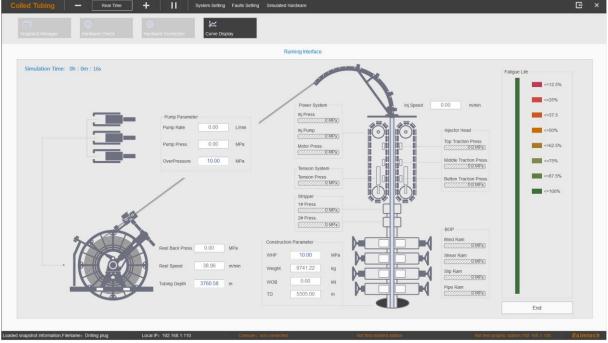


Figure 5 Master control running interface

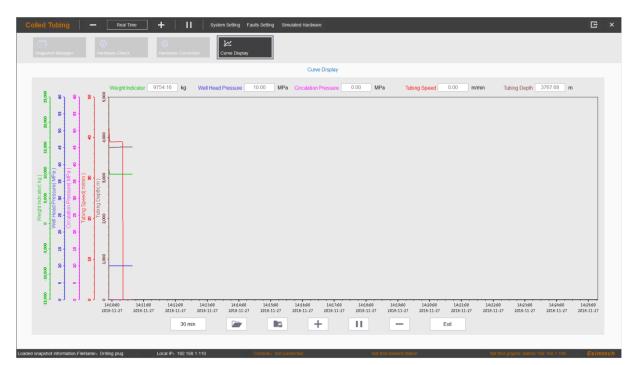


Figure 6 Plot display interface

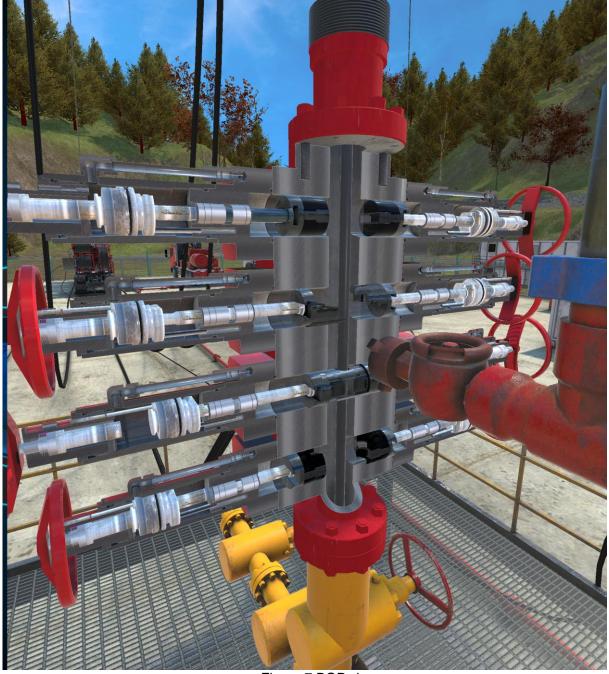


Figure 7 BOP view

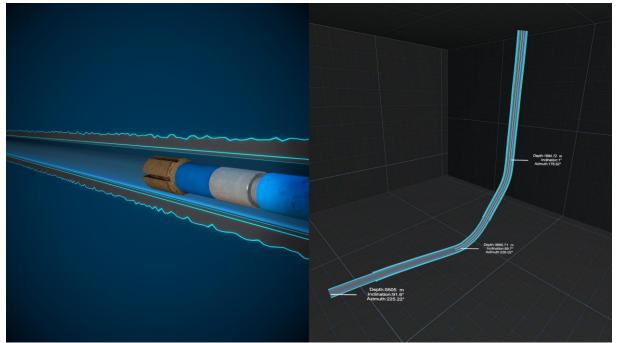


Figure 8 Downhole view of graphics system



Figure 9 Operation cabinet view